Trend and Time Series Analysis of Vegetation Dynamics Using Satellite Data: A Case Study of Uttarakhand, India

Govind Verma a*, Ashish Mehta a† and Shikha Goswami b‡

a Department of Computer Science, Kumaun University, India.
b Department of Information Technology, GB Pant University, India.

ABSTRACT

In this work, aim is to collect time series data for Normalized Difference Vegetation Index (NDVI) band using google earth engine (GEE) and MOD13A1 V6.1 product for the region of Uttarakhand, Uttarakhand districts and Himachal Pradesh. Thereafter investigation and comprehension of the viability of using MODIS NDVI satellite data time series to identify trends and give a forecast model. Time series data was collected using Google Earth Engine for NDVI indices for the period of the year 2010 to 2022. Trend analysis and time series analysis were performed for collected data. NDVI time series data set is collected using GEE for Uttarakhand state, its districts and Himachal Pradesh State. The Mann-Kendell (MK) method is used to find trend analysis of above regions. NDVI time series data is divided into train and test dataset. Five forecasting models are used to forecast NDVI time series dataset i.e., Long short-term memory (LSTM), Bidirectional Long short-term memory (BiLSTM), Support vector regression (SVR), Autoregressive Integrated Moving (ARIMA), Adaptive Neuro fuzzy interference system (ANFIS) models are trained using train data and are used to generate the predicted value. The predicted value is then compared with test data using various metrics for forecasting NDVI times series. Trend analysis of NDVI shows an increasing trend in
NDVI values for Uttarakhand and its districts as well as Himachal Pradesh. ANFIS model resulted R² value of 0.6702, Stacked LSTM model resulted R² value of 0.7541, Bidirectional LSTM model resulted with highest R² value of 0.8365, Autoregressive Integrated Moving Average (ARIMA) model resulted with lowest R² value of 0.153, SVR model resulted with R² value of 0.6719.

Keywords: NDVI; LSTM; ARIMA; ANFIS.

1. INTRODUCTION

Vegetation is an essential part of terrestrial ecosystems and regulates the world's energy and material cycles in ways that cannot be replaced. It's a significant indicator of terrestrial metabolic processes and, exhibits remarkable spatiotemporal variation. For a better knowledge of biochemical processes and their possible feedback on the climate system, systematic monitoring of analysis of vegetation dynamics is necessary. This will improve our ability to anticipate, mitigate and adapt to future climate change and hence vegetation sustainability [1,2]. The Google Cloud Platform powers the Google Earth Engine (GEE), a cloud-based computation and analysis tool for geospatial data. It has various freely available remote sensing datasets and is leveraged to gather Normalized Difference Vegetation Index (NDVI) and Enhanced Vegetation Index (EVI) time series data related to vegetation for a region of interest without directly accessing satellite imagery [3,4]. NDVI and gives a numerical value for the vegetation for an area of interest by measuring the difference between near-infrared and red. The NDVI value ranged from -1 to 1, where positive values indicate greater greenery (vigour) and negative values indicate surfaces that are not covered by vegetation, such as urban areas, bare soil or land, water, or ice. EVI also quantifies vegetation greenery and takes into consideration for corrections to be made in atmospheric conditions, canopy background noise and is more sensitive in areas with dense vegetation while calculating indices [5-7]. Researchers have applied MK trend analysis to NDVI and EVI time series datasets to find out trends in the growth of vegetation [8-10]. The statistical autoregressive integrated moving average (ARIMA), Markov chain model, multiple layer perceptron (MLP), artificial neural network (ANN), and prediction methods have all been developed and utilized to predict NDVI time series. But these methods have limitations like the parametric model ARIMA requires stationary data, Markov chain model only considers the present state of knowledge to predict the future. The findings of ANN, a neural network model, are less effective than those of recently recurrent neural networks since it lacks memory to store the information of previous data [11-13]. A comprehensive study is done and it is found that till now no research have been published for NDVI time series prediction for Uttarakhand region using deep learning models LSTM BiLSTM. A kind of machine learning called deep learning (DL) uses neural networks with several hidden and specific layers as well as deeper connections. The most effective neural networks that are applied for NDVI forecasting are Convolutional Neural Network (CNN), Recurrent Neural Network (RNN), and Long-Short Term Memory Network (LSTM) [14]. Contrasted the effectiveness of three statistical techniques, one of which is a traditional statistics LASSO, a technique that uses the least absolute shrinkage and selection operator, DL approach (LSTM) and an ML method (RF) for predicting rice yield in China [15,16]. The outcomes demonstrated that LSTM performed better than other statistical methods. The overall objective of the study is to study the vegetation dynamics of Uttarakhand and its districts and thereafter fit a forecast model which gives a better prediction values.

The goals of this paper are: (1) to collect NDVI and EVI time-series data for Uttarakhand and its districts region 2) to apply MK statistical method to find trends of NDVI time series dataset (3) to develop and evaluate an LSTM model for NDVI time series dataset. (4) Compare the result obtained from LSTM models applied to NDVI data with other traditional forecasting models.

2. STUDY CONTEXT AND METHODOLOGY

2.1 Study Area

The territory of Uttarakhand State is located in south of Asia Continent and North of India with an area of 53,485 sq. km. The territory extends from 28°43' - 31°27' N latitudes and 77°34' - 81°02' E longitudes. The orography of Uttarakhand is quite diverse with mountain systems, plains and valleys, snow cover. Its area is covered by 86% mountainous and 65% forest. The State has 13 districts out of which ten
Fig. 1. Study Area: Uttarakhand

Fig. 2. Steps undertaken to collect time series NDVI and EVI dataset for Uttarakhand and its districts
regions (Uttarkashi, Tehri, Pithoragarh, Almora, Nainital, Rudraprayag, Chamoli, Pauni, Gopeswar, Champawat) are hilly districts and three Regions comes under (U. S. Nagar, Dehradun, Haridwar) plain as well as and hilly districts. The majority of hilly regions are rural areas and plain regions are urban areas. The population of Uttarakhand is 1.14 Crores (year 2021). Figure 1 shows study area and population density map of Uttarakhand retrieved using GEE and GPWv411: Population Density dataset [1].

### 2.2 Dataset

The NDVI TS is collected using GEE for the region of Uttarakhand and its districts from the 16-dayMODIS NDVI product at 250 m spatial resolution (MOD13Q1 collection 6) for the period (2000-2022(July)). MODI13Q1 Terra Vegetation data set is available in GEE and has bands of NDVI and EVI. Polygon of interest is created for Uttarakhand, its districts and Himachal region, then NDVI and EVI time series values were extracted using GEE APIs for the time period of year 2000 to year 2022. Fig. 2 summarizes NDVI and EVI time series data collection for further analysis.

### 2.3 Methodology

Time series data collected by following steps given in section 2.2 were input to MK test and different types of LSTM models. Fig. 3 shows the steps that were followed to do trend analysis and forecasting.

#### 2.3.1 Mann-Kendell test

The non-parametric MK [17] test is commonly used in the various datasets of meteorology and hydrology to find trends in time series data. MK is applied to the NDVI time series data gathered using steps given in section 2.2 to identify trends. MK test is a non-parametric test and does not require ordered data to be any in kind of distribution. The following steps were followed to apply the MK statistic:

a. Each element in time series data is compared to the following data item of the series and if there is a higher value in subsequent data, the $S$ is increased by 1 and otherwise $S$ is decreased by 1.

b. Calculate the value of $S$ i.e MK statistic: Equations 2 and 3 below are used to calculate the value of $S$ i.e MK statistic.

c. Variation of $S$ is calculated using Equation 4.

d. Normalized statics $Z$ is calculated using Equation 1.

e. Calculate the probability using Equation 5 associated with the $Z$ calculated in step d.

f. The trend in time series is deduced as follows:
i) decreasing if $Z$ is negative and computed probability is greater than the level of significance (95% typically)

ii) increasing if $Z$ is negative and computed probability is greater than the level of significance (95% typically)

iii) no trend if the computed probability is less than the level of significance (95% typically).

iv) A simple Sen’s Method to calculate magnitude of trend is calculated using Equation 6.

\[
Z = Z = \begin{cases} 
\frac{S - 1}{\sqrt{\text{Var}(S)}} & \text{if } S > 0 \\
0 & \text{if } S = 0 \\
\frac{S + 1}{\sqrt{\text{Var}(S)}} & \text{if } S < 0 
\end{cases} 
\]

(1)

\[
S = \sum_{k=1}^{n-1} \sum_{j=k+1}^{n} \text{sgn}(x_j - x_k) 
\]

(2)

\[
\text{sgn}(x_j - x_k) = \begin{cases} 
+1 & \text{if } (x_j - x_k) > 0 \\
0 & \text{if } (x_j - x_k) = 0 \\
-1 & \text{if } (x_j - x_k) < 0 
\end{cases} 
\]

(3)

\[
\text{Var}(S) = \frac{n(n - 1)(2n + 5) - \sum_{i=1}^{m} t_i(t_i - 1)(2t_i + 5)}{18} 
\]

(4)

\[
f(Z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{Z^2}{2}} 
\]

(5)

\[
\beta = \text{median} \left( \frac{x_j - x_k}{j-i}, j > i \right) 
\]

(6)

---

**Fig. 4. LSTM cell arrangement**

**Fig. 5. Architecture of LSTM cell with forget, input and output gate**
2.3.2 LSTM and different LSTM networks

Hochreiter S et al. [18] Introduced the LSTM and compared to Recurrent Neural Networks, it has showed better performance in forecasting time series data. LSTM handles long-term dependencies and fixes the vanishing gradient issue by remembering all of the prior information that the network has seen while forgetting any information that is not relevant. This is achieved by applying different activation function layers called gates. LSTM cell has three gates. The forget gate determines using equation 1 what information must be regarded and what can be disregarded. The value of the fresh information carried by the input is measured by the input gate using equation 2. Output gate uses equation 6 which chooses what output (next Hidden State) the present Internal Cell State will produce. Fig. 4 show LSTM cell arrangement and Fig. 5 show architecture of a LSTM cell.

\[ f_t = \sigma(W_{fh} h_{t-1} + W_{fx} x_t + b_f) \]  
\[ i_t = \sigma(W_{ih} h_{t-1} + W_{ix} x_t + i) \]  
\[ g_t = \tanh(W_{gh} h_{t-1} + W_{gx} x_t + b_g) \]  
\[ f_t = \sigma(W_{fh} h_{t-1} + W_{fx} x_t + b_f) \]  
\[ c_t = f_t \cdot c_{t-1} + i_t \cdot g_t \]  
\[ o_t = \sigma(W_{oh} h_{t-1} + W_{ox} x_t + b_o) \]  
\[ h_t = o_t \cdot x_t \cdot \tanh(c_t) \]  

A variant of LSTM models: Stacked and Bidirectional LSTM types of LSTM is used for forecasting NDVI time series dataset.

2.3.3 Adaptive Neuro FIS (ANFIS)

The Takagi–Sugeno FIS provides the foundation for an ANFIS or adaptable network-based FIS. In the early 1990s, this method was created [19-21]. It can combine the advantages of NNs and FL into a single framework because of the way it incorporates both. Its inference system is based on a set of fuzzy IF-THEN rules with the capacity to learn and estimated nonlinear functions. As a result, ANFIS is called a universal estimator [22]. ANFIS network is made up of a collection of nodes that are arranged in layers to carry out different tasks. Fig. 6 shows ANFIS architecture and consists of six layers, operations of layers are briefly explained as follows:

- **Input layer**: Input signals, which are taken from each of the nodes on this layer, are transferred into other layers.
- **Input Membership Function layer**: This is called the fuzzification layer. ANFIS model uses the current Bell activation function as the membership function in order to divide input values into fuzzy sets.
- **Rule layer**: Each node in this layer expresses the rules and number of the Sugeno fuzzy logic deduction system.
- **Normalization Layer**: Each node in this layer assumes all the nodes coming from rule layer as the input value, and it calculates the normalized ignition level of each rule.
- **Output Membership Function layer**: This is the debugging layer. In this layer, weighted result values of a rule, which is given in each node, are calculated.
- **Output Layer**: This is the sum layer. There is only one node in this layer, and it is tagged with \( \sum \). Here, output values of each node in the fifth layer are added to each other, and a real value of ANFIS system is obtained.

2.3.4 Prediction accuracy measures

Several statistical metrics were used to evaluate the model's ability to predict outcomes. Following are the metrics used to measure the accuracy of the model:

i) Root Mean Square Metric (RMSE)

The root mean square metric is used to measure the accuracy of prediction and can be calculated by using equation 14.

\[ \text{RMSE} = \frac{1}{n} \sqrt{\sum_{i=1}^{n} (\hat{y}(i) - y(i))^2} \]  

Where \( \hat{y}(i) \) is the predicted value and \( y(i) \) is the actual value.

ii) The correlation between the actual and predicted production is indicated by the determination coefficient (\( R^2 \)) and calculated using equation 15, which ranges from zero to one (both inclusive). One number denotes a perfect model, whereas zero denotes a random one.
Fig. 6. ANFIS Architecture

\[ R^2 = \frac{\sum_{i=1}^{n}(y - \bar{y})(\hat{y} - \bar{y})^2}{\sqrt{\sum_{i=1}^{n}(y - \bar{y})^2 \sum_{i=1}^{n}(\hat{y} - \bar{y})^2}} \]  \tag{15}

where \( y \) is actual output, \( \hat{y} \) is the predicted value, \( \bar{y} \) is the average of actual value, \( \bar{\hat{y}} \) is the average of the predicted value.

iii) Mean absolute error (MAE) the absolute error existing between the real and predicted output and calculated using equation 16.

\[ MAE = \frac{1}{n} \sum_{i=1}^{n} |y - \hat{y}| \]  \tag{16}

Where \( y \) is the actual value and \( \hat{y} \) is the predicted value.

iv) Mean square error (MSE) the average squared error existing between the predicted and real output and calculated using equation 17.

\[ MSE = \frac{1}{n} \sum_{i=1}^{n} (y - \hat{y})^2 \]  \tag{17}

Where \( y \) is the actual value and \( \hat{y} \) is the predicted value.

3. RESULTS AND DISCUSSION

The current research is an experimental study to monitor the vegetation trends and dynamics of Uttarakhand state and its districts. Fig. 7 shows the time series data extracted for Uttarakhand region. The MK test and Sen’s slope were used to access the trends for NDVI and forecasting models were applied time series NDVI dataset of Uttarakhand.

Trend analysis is carried out on the NDVI variables, and the results of MK test along with the Z value and Sen’s slope giving the magnitude of trend are given in Table 1. The table clearly shows strong growing trends in NDVI for Uttarakhand, its districts and Himachal Pradesh. All districts of Uttarakhand show an increasing trend of NDVI with a varied magnitude of slope. Rudraprayag, Chamoli, Uttarkashi and Pithoragarh show an increasing trend in NDVI values but the magnitude of increasing slope is less than in other districts. Dehradun and Almora show an increasing trend in NDVI values with a significant magnitude of increase in NDVI values. When Uttarakhand and Himachal Pradesh NDVI slope is compared both states have significant growth in NDVI values.

As stated earlier forecasting models were applied to NDVI times series data set, Figs. 8-15 along with Table 2 shows the results of time series forecasting models applied for forecasting in test data of NDVI. These models were first trained with 80 percent of NDVI data (Training Data) and then trained model is used to generate predicted values of NDVI. Thereafter, the predicted values were compared to 20 percent of NDVI data (Test data) using various metrics discussed in previous section. Results obtained after various hyper parameters values pertaining to models were applied and the metrics values that resulted in \( R^2 \) value close to 1 is selected were chosen as best model for forecasting. ANFIS model resulted \( R^2 \) value of 0.6702, RMSE value of 0.038015848, MAE value of 0.027941089, MSE value of 0.001445205 and MAPE value of 0.061556184. Stacked LSTM model resulted \( R^2 \) value of 0.7541, RMSE value 0.036419336, MAE value of 0.026412653, MSE value of 0.00126368 and MAPE value of 0.056518498. Bidirectional LSTM model resulted with highest \( R^2 \) value of 0.8365, RMSE value 0.027757431, MAE value of 0.021041361, MSE value of 0.000770475 and
MAPE value of 0.044492608. ARIMA model resulted with lowest $R^2$ value of 0.153, RMSE value 0.061512055, MAE value of 0.04393482, MSE value of 0.003783733 and MAPE value of 0.095554665. SVR model resulted with $R^2$ value of 0.6719, RMSE value 0.037469169, MAE value of 0.0275219099, MSE value of 0.0014039386 and MAPE value of 0.61063698.

Fig. 7. NDVI and EVI time series dataset for Uttarakhand region

Table 1. Mann Kendall Test performed on NDVI data obtained from period of 01.01.2000 to 01.03.2022 for Uttarakhand districts, Uttarakhand and Himachal Pradesh

<table>
<thead>
<tr>
<th>SN</th>
<th>Uttarakhand Districts</th>
<th>Trend</th>
<th>Mann_Kendall_Test</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>T</td>
</tr>
<tr>
<td>1</td>
<td>Pauri Garwal</td>
<td>increasing</td>
<td>0.0001492</td>
</tr>
<tr>
<td>2</td>
<td>Dehradun</td>
<td>increasing</td>
<td>0.0001499</td>
</tr>
<tr>
<td>3</td>
<td>Bageshwar</td>
<td>increasing</td>
<td>0.0001017</td>
</tr>
<tr>
<td>4</td>
<td>Rudraprayag</td>
<td>increasing</td>
<td>8.2191e-5</td>
</tr>
<tr>
<td>5</td>
<td>Tehri</td>
<td>increasing</td>
<td>0.0001198</td>
</tr>
<tr>
<td>6</td>
<td>Pithoragarh</td>
<td>increasing</td>
<td>6.775e-05</td>
</tr>
<tr>
<td>7</td>
<td>Champawat</td>
<td>increasing</td>
<td>0.000125</td>
</tr>
<tr>
<td>8</td>
<td>Udham Singh Nagar</td>
<td>increasing</td>
<td>0.00014285</td>
</tr>
<tr>
<td>9</td>
<td>Nainital</td>
<td>increasing</td>
<td>0.00012806</td>
</tr>
<tr>
<td>10</td>
<td>Chamoli</td>
<td>increasing</td>
<td>5.92e-05</td>
</tr>
<tr>
<td>11</td>
<td>Hardwar</td>
<td>increasing</td>
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<tr>
<td>12</td>
<td>Almora</td>
<td>increasing</td>
<td>0.0001459</td>
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<tr>
<td>13</td>
<td>Uttarkashi</td>
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<td>6.593e-05</td>
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</table>

<table>
<thead>
<tr>
<th>States</th>
<th>Trend</th>
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</tr>
</thead>
<tbody>
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<td>1</td>
<td>Uttarakhand</td>
<td>increasing</td>
</tr>
<tr>
<td>2</td>
<td>Himachal Pradesh</td>
<td>increasing</td>
</tr>
</tbody>
</table>
Fig. 8. ANFIS results: Actual Vs Predicted NDVI

Fig. 9. ANFIS: Scatter Plot Actual Vs Predicted NDVI

Fig. 10. Stacked LSTM results: Actual Vs Predicted NDVI

Fig. 11. Stacked LSTM: Scatter Plot Actual Vs Predicted NDVI

Fig. 12. LSTM Bidirectional results: Actual Vs Predicted NDVI

Fig. 13. Bidirectional LSTM: Scatter Plot Actual Vs Predicted NDVI
Table 2. Statistical results (testing period) of the five-time series forecasting models

<table>
<thead>
<tr>
<th>SN</th>
<th>Method</th>
<th>Root Mean Squared Error</th>
<th>R²</th>
<th>Mean Absolute Error</th>
<th>Mean Squared Error</th>
<th>Mean Absolute Percentage Error</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>ANFIS</td>
<td>0.038015848</td>
<td>0.6702</td>
<td>0.027941089</td>
<td>0.001445205</td>
<td>0.061556184</td>
</tr>
<tr>
<td>2</td>
<td>Stacked LSTM</td>
<td>0.036419336</td>
<td>0.7541</td>
<td>0.026412653</td>
<td>0.001326368</td>
<td>0.056518498</td>
</tr>
<tr>
<td>3</td>
<td>Bidirectional LSTM</td>
<td>0.027757431</td>
<td>0.8365</td>
<td>0.021041361</td>
<td>0.000770475</td>
<td>0.044492608</td>
</tr>
<tr>
<td>4</td>
<td>ARIMA</td>
<td>0.061512055</td>
<td>0.153</td>
<td>0.04393482</td>
<td>0.003783733</td>
<td>0.095554665</td>
</tr>
<tr>
<td>5</td>
<td>SVR</td>
<td>0.037469169</td>
<td>0.6719</td>
<td>0.0275219099</td>
<td>0.0014039386</td>
<td>0.061063698</td>
</tr>
</tbody>
</table>

Fig. 14. SVR results: Actual Vs Predicted NDVI

Fig. 15. SVR Scatter Plot Actual Vs Predicted NDVI

Fig. 16. Mean NDVI for period from year 2000-2004
Fig. 17. Mean NDVI for period from year 2020-2022

Fig. 18. Difference of NDVI mean from year 2000-2021
Fig. 19. Raster Histogram of differenced NDVI mean pixel values of average image of year 2000 and 2021

Fig. 16 shows a color-coded map of Uttarakhand mean NDVI for the period of years 2000-2004, similarly Fig. 17 shows a color-coded map of Uttarakhand mean NDVI for the period of years 2020-2022 and Fig. 18 shows a color-coded map of Uttarakhand which depicts the differences of NDVI mean of year 2000 and 2022. Fig. 19 shows histogram of NDVI difference of NDVI mean per pixel value of the years for the year 2000 and 2022 and the frequency of most changed pixel (difference NDVI value is -0.0588) found has a frequency of greater than 1200 pixels.

4. CONCLUSION

In this research, NDVI time series data for the period of the years 2000-2022 were collected for Uttarakhand, its Districts and Himachal Pradesh using GEE. Trend analysis is done for the collected time series data and found that Uttarakhand and its districts shows an increasing trend in NDVI values from year 2000 to 2022 with a varied magnitude. District Uttarkashi shows an increasing trend in NDVI values but with minimum magnitude. Uttarakhand state NDVI shows better magnitude in of increasing trend as compared to Himachal Pradesh. LSTM Time series forecasting methods shows better results than traditional forecasting methods. In future, more time series dataset can be added to analyse the impact on NDVI for a particular region.

COMPETING INTERESTS

Authors have declared that no competing interests exist.

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